# EXISTENCE AND ULAM STABILITY OF K-GENERALIZED $\psi$ -HILFER FRACTIONAL PROBLEM

# Abdelkrim Salim, Mouffak Benchohra, Jamal Eddine Lazreg

# Djillali Liabes University of Sidi Bel-Abbes, P.O. Box 89 Sidi Bel Abbes 22000, Algeria.

## ABSTRACT

In this paper, we prove existence, uniqueness stability results for a class of initial value problem for fractional differential equations involving generalized  $\psi$ -Hilfer fractional derivative. The result is based on the Banach contraction mapping principle. In addition, two examples are given to illustrate our results.

## 1. INTRODUCTION

The differential and fractional integral calculus generalizes the notions of integration and derivation of integer order, its history dates back to 1695, see [1, 2, 3, 4, 8, 23] and the references therein. In these last few decades, the application of fractional differential calculus has been made in various fields of research and engineering during the last decades; in control theory, bio-chemistry, economics, etc. There are various types of fractional derivatives such as, Riemann-Liouville fractional derivative, Caputo fractional derivative, Hadamard fractional derivative, Hilfer fractional derivative, Katugampola fractional derivative, Caputo-Fabrizio fractional derivative, Atangana-Baleanu-Caputo fractional derivative,  $\psi$ -fractional derivatives and many others, see [15, 16, 17, 18, 19, 9] and the references therein. Diaz *et al.* [6] have presented *k*-gamma and *k*-beta functions and demonstrated a number of their properties. Important properties can be found in the article [10], and very recently (see [5, 11, 12]), many researchers managed to generalize various fractional integrals and derivatives. Sousa and Capelas de Oliveira, in [21], introduce another so-called  $\psi$ -Hilfer fractional derivative with respect to a given function, and present some important properties concerning this type of fractional operator. They proved numerous results in [21, 20, 22].

Motivated by the works of the papers mentioned above, in this paper, by using the functions k-gamma, k-beta and k-Mittag-Leffler, we generalize the  $\psi$ -Hilfer fractional derivative and set some of its properties. Then, we propose a generalized Gronwall inequality, which will be used in an application. Finally, we consider the initial value problem with k-generalized  $\psi$ -Hilfer type fractional differential equation :

$$\begin{pmatrix} H \mathscr{D}_{a+}^{\vartheta,r;\psi} x \end{pmatrix}(t) = f(t,x(t)), \ t \in (a,b],$$
(1)

$$\left(\mathscr{J}_{a+}^{k(1-\xi),k;\Psi}x\right)(a^+) = x_0,\tag{2}$$

where  ${}_{k}^{\mathcal{H}} \mathscr{D}_{a+}^{\vartheta,r;\Psi}$ ,  $\mathscr{J}_{a+}^{k(1-\xi),k;\Psi}$  are the *k*-generalize  $\psi$ -Hilfer fractional derivative of order  $\vartheta \in (0,1)$  and type  $r \in [0,1]$  defined in Section 2, and *k*-generalize  $\psi$ -fractional integral of order  $k(1-\xi)$  defined in [13] respectively, where  $\xi = \frac{1}{k}(r(k-\vartheta) + \vartheta)$ ,  $\theta < k$ ,  $x_0 \in \mathbb{R}$ , k > 0 and  $f \in C([a,b] \times \mathbb{R},\mathbb{R})$ .

The following are the primary novelties of the current paper :

- 1. Given that the  $\psi$ -Hilfer fractional derivative unifies a larger number of fractional derivatives in a single fractional operator, defining the k-generalized  $\psi$ -Hilfer fractional derivative allows us to encompass more fractional operators, opening the door to new applications.
- 2. The results of this study are generalizations of several results obtained in [21, 12, 1, 2, 3].

The present paper is organized as follows. In Section 2, some notations are introduced and we recall some preliminaries about  $\psi$ -Hilfer fractional derivative, the functions *k*-gamma, *k*-beta and *k*-Mittag-Leffler and some auxiliary results, then we define the *k*-generalize  $\psi$ -Hilfer type fractional derivative and give some necessary theorems and lemmas. In Section 3, a result for the problem (1)-(2) are presented which is based on Banach contraction principle. In Section 4, we study the Ulam-Hyers-Rassias (U-H-R) stability for our problem (1)-(2). Finally, in the last section, we give two examples to illustrate the applicability of our results.

#### 2. PRELIMINARIES

First, we present the weighted spaces, notations, definitions, and preliminary facts which are used throughout this paper. Let  $0 < a < b < \infty$ , J = [a,b],  $\vartheta \in (0,1)$ ,  $r \in [0,1]$ , k > 0 and  $\xi = \frac{1}{k}(r(k - \vartheta) + \vartheta)$ . By  $C(J, \mathbb{R})$  we denote the Banach space of all continuous functions from J into  $\mathbb{R}$  with the norm

$$||x||_{\infty} = \sup\{|x(t)| : t \in J\}.$$

 $AC^n(J,\mathbb{R}), C^n(J,\mathbb{R})$  be the spaces of continuous functions, *n*-times absolutely continuous and *n*-times continuously differentiable functions on *J*, respectively. Consider the weighted Banach space

$$C_{\xi;\psi}(J) = \left\{ x : (a,b] \to \mathbb{R} : t \to (\psi(t) - \psi(a))^{1-\xi} x(t) \in C(J,\mathbb{R}) \right\},\$$

with the norm

$$||x||_{C_{\xi;\psi}} = \sup_{t\in J} \left| (\psi(t) - \psi(a))^{1-\xi} x(t) \right|,$$

and

$$C^{n}_{\xi;\psi}(J) = \left\{ x \in C^{n-1}(J) : x^{(n)} \in C_{\xi;\psi}(J) \right\}, n \in \mathbb{N},$$
  
$$C^{0}_{\xi;\psi}(J) = C_{\xi;\psi}(J),$$

with the norm

$$\|x\|_{C^n_{\xi;\psi}} = \sum_{i=0}^{n-1} \|x^{(i)}\|_{\infty} + \|x^{(n)}\|_{C_{\xi;\psi}}$$

Consider the space  $X_{\Psi}^{p}(a,b)$ ,  $(c \in \mathbb{R}, 1 \le p \le \infty)$  of those real-valued Lebesgue measurable functions g on [a,b] for which  $\|g\|_{X_{\Psi}^{p}} < \infty$ , where the norm is defined by

$$\|g\|_{X^p_{\Psi}} = \left(\int_a^b \psi'(t)|g(t)|^p dt\right)^{\frac{1}{p}},$$

where  $\psi$  is an increasing and positive function on [a,b] such that  $\psi'$  is continuous on [a,b] with  $\psi(0) = 0$ . In particular, when  $\psi(x) = x$ , the space  $X^{\psi}_{\psi}(a,b)$  coincides with the  $L_p(a,b)$  space. Recently, in [6], Diaz and Petruel have defined new functions called *k*-gamma and *k*-beta functions given by

$$\Gamma_k(\alpha) = \int_0^\infty t^{\alpha-1} e^{-\frac{t^k}{k}} dt, \alpha > 0.$$

- For  $k \to 1 : \Gamma_k(\alpha) \to \Gamma(\alpha)$ .
- We have :

$$\Gamma_{k}(\alpha) = k^{\frac{\alpha}{k}-1} \Gamma\left(\frac{\alpha}{k}\right), \ \Gamma_{k}(\alpha+k) = \alpha \Gamma_{k}(\alpha), \ \Gamma_{k}(k) = \Gamma(1) = 1$$

Furthermore *k*-beta function is defined as follows :

$$B_k(\alpha,\beta) = \frac{1}{k} \int_0^1 t^{\frac{\alpha}{k}-1} (1-t)^{\frac{\beta}{k}-1} dt$$

so that

$$B_k(\alpha,\beta) = \frac{1}{k} B\left(\frac{\alpha}{k},\frac{\beta}{k}\right), B_k(\alpha,\beta) = \frac{\Gamma_k(\alpha)\Gamma_k(\beta)}{\Gamma_k(\alpha+\beta)}$$

The Mittag-Leffler function can also be refined into the *k*-Mittag-Leffler function defined as follows

$$E_k^{\alpha,\beta}(x) = \sum_{i=0}^{\infty} \frac{x^i}{\Gamma_k(\alpha i + \beta)}, \alpha, \beta > 0.$$

Now, we give all the definitions to the different fractional operators used throughout this paper.

**Definition 1** ([13]) (k-Generalized  $\psi$ -fractional Integral) Let  $g \in X^p_{\psi}(a, b)$  and [a, b] be a finite or infinite interval on the real axis  $\mathbb{R} = (-\infty, \infty)$ ,  $\psi(t) > 0$  be an increasing function on (a, b] and  $\psi'(t) > 0$  be continuous on (a, b) and  $\vartheta > 0$ . The generalized k-fractional integral operator of a function f (left-sided) of order  $\vartheta$  is defined by

$$\mathscr{J}_{a+}^{\vartheta,k;\Psi}g(t) = \frac{1}{k\Gamma_k(\vartheta)} \int_a^t \frac{\Psi'(s)g(s)ds}{(\Psi(t) - \Psi(s))^{1-\frac{\vartheta}{k}}},$$

with k > 0.

**Remark 1** Nápoles Valdés ([11]) gave a more generalized fractional integral operators defined by

$$\mathscr{J}_{G,a+}^{\vartheta,k;\psi}g(t) = \frac{1}{k\Gamma_k(\vartheta)} \int_a^t \frac{\psi'(s)g(s)ds}{G(\psi(t) - \psi(s), \frac{\vartheta}{k})}$$

where  $G(z, \vartheta) \in AC[a, b]$ .

**Theorem 1** ([11]) Let  $g: [a,b] \to \mathbb{R}$  be an integrable function, and take  $\vartheta > 0$  and k > 0. Then  $\mathscr{J}_{G,a+}^{\vartheta,k;\psi}g$  exists for all  $t \in [a,b]$ .

**Theorem 2** ([11]) Let  $g \in X_{\Psi}^{p}(a,b)$  and take  $\vartheta > 0$  and k > 0. Then  $\mathscr{J}_{G,a+}^{\vartheta,k;\Psi}g \in C([a,b],\mathbb{R})$ .

**Lemma 3** [14] Let  $\vartheta > 0$ , r > 0 and k > 0. Then, we have the following semigroup property given by

$$\mathcal{J}_{a+}^{\vartheta,k;\psi}\mathcal{J}_{a+}^{r,k;\psi}f(t) = \mathcal{J}_{a+}^{\vartheta+r,k;\psi}f(t) = \mathcal{J}_{a+}^{r,k;\psi}\mathcal{J}_{a+}^{\vartheta,k;\psi}f(t).$$

**Lemma 4** [14] Let  $\vartheta$ , r > 0 and k > 0. Then, we have

$$\mathscr{J}_{a+}^{\vartheta,k;\psi}[\psi(t)-\psi(a)]^{\frac{r}{k}-1} = \frac{\Gamma_k(r)}{\Gamma_k(\vartheta+r)}(\psi(t)-\psi(a))^{\frac{\vartheta+r}{k}-1}.$$

**Theorem 5** [14] Let  $0 < a < b < \infty$ ,  $\vartheta > 0, 0 \le \xi < 1$ , k > 0 and  $x \in C_{\xi;\psi}(J)$ . If  $\frac{\vartheta}{k} > 1 - \xi$ , then  $\left(\mathscr{J}_{a+}^{\vartheta,k;\psi}x\right)(a) = \lim_{t \to a^+} \left(\mathscr{J}_{a+}^{\vartheta,k;\psi}x\right)(t) = 0.$ 

We are now able to define the k-generalized  $\psi$ -Hilfer derivative as follows.

**Definition 2** [14] (2021) (k-Generalized  $\psi$ -Hilfer Derivative) Let  $n-1 < \frac{\vartheta}{k} \le n$  with  $n \in \mathbb{N}$ , J = [a, b] an interval such that  $-\infty \le a < b \le \infty$  and  $g, \psi \in C^n([a, b], \mathbb{R})$  two functions such that  $\psi$  is increasing and  $\psi'(t) \ne 0$ , for all  $t \in J$ . The k-generalized  $\psi$ -Hilfer fractional derivative (left-sided)  ${}^H_k \mathscr{D}^{\vartheta,r;\psi}_{a+}(\cdot)$  of a function g of order  $\vartheta$  and type  $0 \le r \le 1$ , with k > 0 is defined by

$$\begin{split} {}^{H}_{k} \mathscr{D}^{\vartheta, r; \Psi}_{a+} g\left(t\right) &= \left( \mathscr{J}^{r(kn-\vartheta), k; \Psi}_{a+} \left(\frac{1}{\Psi'\left(t\right)} \frac{d}{dt}\right)^{n} \left(k^{n} \mathscr{J}^{(1-r)(kn-\vartheta), k; \Psi}_{a+} g\right) \right) \left(t\right) \\ &= \left( \mathscr{J}^{r(kn-\vartheta), k; \Psi}_{a+} \delta^{n}_{\Psi} \left(k^{n} \mathscr{J}^{(1-r)(kn-\vartheta), k; \Psi}_{a+} g\right) \right) \left(t\right), \end{split}$$

where  $\delta_{\psi}^{n} = \left(\frac{1}{\psi'(t)}\frac{d}{dt}\right)^{n}$ .

**Lemma 6** [14] Let t > a,  $\vartheta > 0, 0 \le r \le 1, k > 0$ . Then for  $0 < \xi < 1; \xi = \frac{1}{k} (r(k - \vartheta) + \vartheta)$ , we have  $\begin{bmatrix} H \otimes^{\vartheta, r; \Psi} (y_k(s) - y_k(s)) \xi^{-1} \end{bmatrix} (t) = 0$ 

$$\begin{bmatrix} H \mathscr{D}_{a+}^{\vartheta,r;\psi} \left( \psi(s) - \psi(a) \right)^{\xi-1} \end{bmatrix} (t) = 0$$

**Theorem 7** [14] If  $f \in C^n_{\xi;\psi}[a,b], n-1 < \vartheta < n, 0 \le r \le 1$ , where  $n \in \mathbb{N}$  and k > 0, then

$$\left(\mathscr{J}_{a+}^{\vartheta,k;\psi}{}_{k}^{H}\mathscr{D}_{a+}^{\vartheta,r;\psi}f\right)(t) = f(t) - \sum_{i=1}^{n} \frac{(\psi(t) - \psi(a))^{\xi-i}}{k^{i-n}\Gamma_{k}(k(\xi-i+1))} \left\{\delta_{\psi}^{n-i}\left(\mathscr{J}_{a+}^{k(n-\xi),k;\psi}f(a)\right)\right\},$$

where

$$\xi = \frac{1}{k} \left( r(kn - \vartheta) + \vartheta \right).$$

• *For* n = 1 :

$$\left(\mathscr{J}_{a+}^{\vartheta,k;\psi}{}_{k}^{H}\mathscr{D}_{a+}^{\vartheta,r;\psi}f\right)(t) = f(t) - \frac{(\psi(t) - \psi(a))^{\xi-1}}{\Gamma_{k}(r(k-\vartheta) + \vartheta)}\mathscr{J}_{a+}^{(1-r)(k-\vartheta),k;\psi}f(a).$$

**Lemma 8** [14] Let  $\vartheta(0,), 0 \le r \le 1$ , and  $x \in C^1_{\xi; \psi}(J)$ , where k > 0, then for  $t \in (a, b]$ , we have

$$\begin{pmatrix} H \mathscr{D}_{a+}^{\vartheta,r;\psi} \mathscr{J}_{a+}^{\vartheta,k;\psi} x \end{pmatrix} (t) = x(t).$$

Now, we consider the Ulam stability for problem (1)–(2) that will be used in Section 4. Let  $x \in C^1_{\xi;\psi}(J), \varepsilon > 0$  and  $v : (a,b] \longrightarrow [0,\infty)$  be a continuous function. We consider the following inequality :

$$\left| \begin{pmatrix} H \mathscr{D}_{a+}^{\vartheta,r;\Psi} x \end{pmatrix}(t) - f(t,x(t)) \right| \le \varepsilon \nu(t), \ t \in (a,b].$$
(3)

**Definition 3** Problem (1)–(2) is Ulam-Hyers-Rassias (U-H-R) stable with respect to v if there exists a real number  $a_{f,v} > 0$  such that for each  $\varepsilon > 0$  and for each solution  $x \in C^1_{\xi;\psi}(J)$  of inequality (3) there exists a solution  $y \in C^1_{\xi;\psi}(J)$  of (1)–(2) with

$$|x(t) - y(t)| \le \varepsilon a_{f,v} v(t), \qquad t \in J.$$

**Remark 2** A function  $x \in C^1_{\xi;\psi}(J)$  is a solution of inequality (3) if and only if there exist  $\sigma \in C_{\xi;\psi}(J)$  such that

1. 
$$|\sigma(t)| \leq \varepsilon v(t), t \in (a,b],$$
  
2.  $\binom{H}{k} \mathscr{D}_{a+}^{\vartheta,r;\Psi} x(t) = f(t,x(t)) + \sigma(t), t \in (a,b].$ 

We give a generalized Gronwall inequality which will be used in Section 4.

**Lemma 9 (The Gronwall inequality)** [14] (2021) Let x, y be two integrable functions and g continuous, with domain [a,b]. Let  $\psi \in C^1[a,b]$  an increasing function such that  $\psi'(t) \neq 0$ ,  $t \in [a,b]$  and  $\vartheta > 0$  with k > 0. Assume that

1. x and y are nonnegative;

2. w is nonnegative and nondecreasing.

• If

$$x(t) \leq y(t) + \frac{w(t)}{k} \int_{a}^{t} \psi'(s) \left[\psi(t) - \psi(s)\right]^{\frac{\vartheta}{k} - 1} x(s) ds,$$

then

$$x(t) \le y(t) + \int_{a}^{t} \sum_{i=1}^{\infty} \frac{\left[w(t)\,\Gamma_{k}\left(\vartheta\right)\right]^{i}}{k\Gamma_{k}\left(\vartheta\right)} \psi'(s) \left[\psi(t) - \psi(s)\right]^{\frac{i\vartheta}{k} - 1} y(s) \, ds,\tag{4}$$

for all  $t \in [a, b]$ .

• If y is a nondecreasing function on [a,b], then,

$$x(t) \leq y(t) \mathbb{E}_{k}^{\vartheta,k}\left(w(t)\Gamma_{k}(\vartheta)\left(\psi(t)-\psi(a)\right)^{\frac{\vartheta}{k}}\right).$$

#### 3. EXISTENCE OF SOLUTIONS

We consider the following fractional differential equation

$$\begin{pmatrix} H \mathscr{D}_{a+}^{\vartheta,r;\Psi} x \end{pmatrix}(t) = w(t), \ t \in (a,b],$$
(5)

where  $0 < \vartheta < 1, 0 \le r \le 1$ , with the condition

$$\left(\mathscr{J}_{a+}^{k(1-\xi),k;\Psi}x\right)(a^{+}) = x_{0},$$
(6)

where  $\xi = \frac{r(k - \vartheta) + \vartheta}{k}$ ,  $x_0 \in \mathbb{R}$ , k > 0, and where  $w \in C(J, \mathbb{R})$  satisfies the functional equation :

$$w(t) = f(t, x(t))$$

The following theorem shows that the problem (5)-(6) have a unique solution.

**Theorem 10** If  $w(\cdot) \in C^1_{\xi;\psi}(J)$ , then x satisfies (5)-(6) if and only if it satisfies

$$x(t) = \frac{(\boldsymbol{\psi}(t) - \boldsymbol{\psi}(a))^{\xi - 1}}{\Gamma_k(k\xi)} x_0 + \left(\mathscr{J}_{a+}^{\vartheta,k;\boldsymbol{\psi}}w\right)(t).$$
(7)

**Proof.** Assume  $x \in C^1_{\xi;\psi}(J)$  satisfies the equations (5) and (6), and applying the fractional integral operator  $\mathscr{J}_{a+}^{\vartheta,k;\psi}(\cdot)$  on both sides of the fractional equation (5), so

$$\left(\mathscr{J}_{a+}^{\vartheta,k;\psi} {}^{H}_{k}\mathscr{D}_{a+}^{\vartheta,r;\psi}x\right)(t) = \left(\mathscr{J}_{a+}^{\vartheta,k;\psi}w\right)(t)$$

and using Theorem 7 and equation (6), we get

$$\begin{aligned} x(t) &= \frac{(\boldsymbol{\psi}(t) - \boldsymbol{\psi}(a))^{\xi - 1}}{\Gamma_k(k\xi)} \mathscr{J}_{a+}^{k(1-\xi),k;\boldsymbol{\psi}} x(a) + \left(\mathscr{J}_{a+}^{\vartheta,k;\boldsymbol{\psi}} w\right)(t) \\ &= \frac{(\boldsymbol{\psi}(t) - \boldsymbol{\psi}(a))^{\xi - 1}}{\Gamma_k(k\xi)} x_0 + \left(\mathscr{J}_{a+}^{\vartheta,k;\boldsymbol{\psi}} w\right)(t). \end{aligned}$$

Let us now prove that if x satisfies equation (7), then it satisfies equations (5) and (6). Applying the fractional derivative operator  ${}^{H}_{k}\mathscr{D}^{\vartheta,r;\Psi}_{a+}(\cdot)$  on both sides of the fractional equation (7), then we get

$$\begin{pmatrix} {}^{H} \mathscr{D}_{a+}^{\vartheta,r;\psi} x \end{pmatrix}(t) = {}^{H}_{k} \mathscr{D}_{a+}^{\vartheta,r;\psi} \left( \frac{(\psi(t) - \psi(a))^{\xi - 1}}{\Gamma_{k}(k\xi)} x_{0} \right) + \begin{pmatrix} {}^{H}_{k} \mathscr{D}_{a+}^{\vartheta,r;\psi} \mathscr{J}_{a+}^{\vartheta,k;\psi} w \end{pmatrix}(t).$$

Using the Lemma 6 and Lemma 8, we obtain equation (5). Now we apply the operator  $\mathscr{J}_{a+}^{k(1-\xi),k;\psi}(\cdot)$  on equation (7), to have

$$\left(\mathscr{J}_{a+}^{k(1-\xi),k;\psi}x\right)(t) = \frac{x_0}{\Gamma_k(k\xi)}\mathscr{J}_{a+}^{k(1-\xi),k;\psi}(\psi(t)-\psi(a))^{\xi-1} + \left(\mathscr{J}_{a+}^{k(1-\xi),k;\psi}\mathscr{J}_{a+}^{\vartheta,k;\psi}w\right)(t).$$

Now, using Lemma 3 and 4, we get

$$\begin{pmatrix} \mathscr{J}_{a+}^{k(1-\xi),k;\Psi} x \end{pmatrix}(t) = \frac{x_0}{\Gamma_k(k\xi)} \mathscr{J}_{a+}^{k(1-\xi),k;\Psi} (\Psi(t) - \Psi(a))^{\xi-1} + \begin{pmatrix} \mathscr{J}_{a+}^{k(1-\xi),k;\Psi} \mathscr{J}_{a+}^{\vartheta,k;\Psi} w \end{pmatrix}(t)$$
  
=  $x_0 + \begin{pmatrix} \mathscr{J}_{a+}^{k(1-\xi)+\vartheta,k;\Psi} w \end{pmatrix}(t).$ 

Using Theorem 5 with  $t \to a$ , we obtain equation (6). This complete the proof.  $\blacksquare$  As a consequence of Theorem 10, we have the following result :

**Lemma 11** Let  $\xi = \frac{r(k-\vartheta) + \vartheta}{k}$  where  $0 < \vartheta < 1$ ,  $0 \le r \le 1$  and k > 0, let  $f: J \times \mathbb{R} \times \mathbb{R} \to \mathbb{R}$ be a continuous function such that  $f(\cdot, x(\cdot)) \in C^1_{\xi; \psi}(J)$ , for any  $x, y \in C_{\xi; \psi}(J)$ . If  $x \in C^1_{\xi; \psi}(J)$ , then x satisfies the problem (1) - (2) if and only if x is the fixed point of the operator  $\mathscr{T}: C_{\xi; \psi}(J) \to C_{\xi; \psi}(J)$  defined by

$$(\mathscr{T}x)(t) = \frac{(\psi(t) - \psi(a))^{\xi - 1}}{\Gamma_k(k\xi)} x_0 + \frac{1}{k\Gamma_k(\vartheta)} \int_a^t \frac{\psi'(s)\varphi(s)ds}{(\psi(t) - \psi(s))^{1 - \frac{\vartheta}{k}}}.$$
(8)

where  $\varphi$  be a function satisfying the functional equation

$$\boldsymbol{\varphi}(t) = f(t, \boldsymbol{x}(t)).$$

The following hypotheses will be used in the sequel : (*Cd.1*) The function  $f: J \times \mathbb{R} \to \mathbb{R}$  is continuous and  $f(\cdot, x(\cdot)) \in C^1_{\xi; \psi}(J)$ , for any  $x \in C_{\xi; \psi}(J)$ .

(*Cd.2*) There exists constant  $\eta > 0$  such that

$$|f(t,x) - f(t,\bar{x})| \le \eta |x - \bar{x}|$$

for any  $x, \bar{x} \in \mathbb{R}$  and  $t \in J$ .

We are now in a position to state and prove our existence result for the problem (1)-(2) based on Banach's fixed point theorem.

Theorem 12 Assume (Cd.1) and (Cd.2) hold. If

$$\mathscr{L} = \frac{\eta \Gamma_k(k\xi) \left(\psi(b) - \psi(a)\right)^{\frac{\nu}{k}}}{\Gamma_k(\vartheta + k\xi)} < 1, \tag{9}$$

then the problem (1)-(2) has a unique solution in  $C_{\xi;\psi}(J)$ .

**Proof.** We show that the operator  $\mathscr{T}$  defined in (8) has a unique fixed point in  $C_{\xi;\psi}(J)$ . Let  $x, y \in C_{\xi;\psi}(J)$  and  $t \in (a, b]$ . Then, for  $t \in J$  we have

$$|\mathscr{T}x(t) - \mathscr{T}y(t)| \leq \frac{1}{k\Gamma_k(\vartheta)} \int_a^t \frac{\psi'(s)|\varphi_1(s) - \varphi_2(s)|dt}{(\psi(t) - \psi(s))^{1-\frac{\vartheta}{k}}},$$

where  $\varphi_1$  and  $\varphi_1$  be functions satisfying the functional equations

$$\varphi_1(t) = f(t, x(t)),$$
  
$$\varphi_2(t) = f(t, y(t)).$$

By (Cd.2), we have

$$\begin{aligned} |\varphi_1(t) - \varphi_2(t)| &= |f(t, x(t)) - f(t, y(t))| \\ &\leq \eta |x(t) - y(t)|. \end{aligned}$$

Therefore, for each  $t \in (a, b]$ 

$$\begin{aligned} |\mathscr{T}x(t) - \mathscr{T}y(t)| &\leq \frac{\eta}{k\Gamma_k(\vartheta)} \int_a^t \frac{\psi'(s)|x(s) - y(s)|dt}{(\psi(t) - \psi(s))^{1 - \frac{\vartheta}{k}}} \\ &\leq \eta ||x - y||_{C_{\xi;\psi}} \mathscr{J}_{a+}^{\vartheta,k;\psi} (\psi(t) - \psi(a))^{\xi - 1}. \end{aligned}$$

By Lemma 4, we have

$$|\mathscr{T}x(t) - \mathscr{T}y(t)| \leq \left[\frac{\eta \Gamma_k(k\xi)}{\Gamma_k(\vartheta + k\xi)} \left(\psi(t) - \psi(a)\right)^{\frac{\vartheta + k\xi}{k} - 1}\right] \|x - y\|_{C_{\xi;\psi}},$$

hence

$$\begin{split} \left| (\boldsymbol{\psi}(t) - \boldsymbol{\psi}(a))^{1-\xi} \left( \mathscr{T} \boldsymbol{x}(t) - \mathscr{T} \boldsymbol{y}(t) \right) \right| &\leq \left[ \frac{\eta \Gamma_k(k\xi) \left( \boldsymbol{\psi}(t) - \boldsymbol{\psi}(a) \right)^{\frac{\vartheta}{k}}}{\Gamma_k(\vartheta + k\xi)} \right] \|\boldsymbol{x} - \boldsymbol{y}\|_{C_{\xi;\boldsymbol{\psi}}} \\ &\leq \left[ \frac{\eta \Gamma_k(k\xi) \left( \boldsymbol{\psi}(b) - \boldsymbol{\psi}(a) \right)^{\frac{\vartheta}{k}}}{\Gamma_k(\vartheta + k\xi)} \right] \|\boldsymbol{x} - \boldsymbol{y}\|_{C_{\xi;\boldsymbol{\psi}}}, \end{split}$$

which implies that

$$\|\mathscr{T}x - \mathscr{T}y\|_{C_{\xi;\psi}} \leq \left[\frac{\eta\Gamma_k(k\xi)\left(\psi(b) - \psi(a)\right)^{\frac{\vartheta}{k}}}{\Gamma_k(\vartheta + k\xi)}\right] \|x - y\|_{C_{\xi;\psi}}.$$

By (9), the operator  $\mathscr{T}$  is a contraction. Hence, by Banach's contraction principle,  $\mathscr{T}$  has a unique fixed point  $x \in C_{\xi;\psi}(J)$ , which is a solution to our problem (1)-(2).

# 4. ULAM-HYERS-RASSIAS STABILITY

**Theorem 13** Assume that in addition to (Cd.1),(Cd.2) and (9), the following hypothesis holds. (Cd.3) There exist a nondecreasing function  $v \in C^1_{\xi;\psi}(J)$  and  $\kappa_v > 0$  such that for each  $t \in J$ , we have

$$\left(\mathscr{J}_{a+}^{\vartheta,k;\psi}v\right)(t)\leq\kappa_{v}v(t),$$

Then the problem (1)-(2) is U-H-R stable with respect to v.

**Proof.** Let  $x \in C^1_{\xi;\psi}(J)$  be a solution if inequality (3), and let us assume that y is the unique solution of the problem

$$\left\{ \begin{array}{l} \left( \begin{matrix} H \mathscr{D}_{a+}^{\vartheta,r;\Psi} \mathbf{y} \\ k \end{matrix} \right)(t) = f\left(t,\mathbf{y}(t)\right); \ t \in (a,b], \\ \left( \mathscr{J}_{a+}^{k(1-\xi),k;\Psi} \mathbf{y} \right)(a^+) = \left( \mathscr{J}_{a+}^{k(1-\xi),k;\Psi} x \right)(a^+) \end{array} \right.$$

By Lemma 11, we obtain for each  $t \in (a, b]$ 

$$\mathbf{y}(t) = \frac{(\boldsymbol{\psi}(t) - \boldsymbol{\psi}(a))^{\xi - 1}}{\Gamma_k(k\xi)} \mathscr{J}_{a+}^{k(1 - \xi), k; \boldsymbol{\psi}} \mathbf{y}(a) + \left(\mathscr{J}_{a+}^{\vartheta, k; \boldsymbol{\psi}} \mathbf{w}\right)(t),$$

where  $w \in C^1_{\xi;\psi}(J)$ , be a function satisfying the functional equation

$$w(t) = f(t, y(t)).$$

Since x is a solution of the inequality (3), by Remark 2, we have

$$\begin{pmatrix} H \mathscr{D}_{a+}^{\vartheta,r;\Psi} x \end{pmatrix}(t) = f(t,x(t)) + \sigma(t), t \in (a,b].$$
(10)

Clearly, the solution of (10) is given by

$$x(t) = \frac{(\boldsymbol{\psi}(t) - \boldsymbol{\psi}(a))^{\xi - 1}}{\Gamma_k(k\xi)} \mathscr{J}_{a+}^{k(1 - \xi), k; \boldsymbol{\psi}} x(a) + \left(\mathscr{J}_{a+}^{\vartheta, k; \boldsymbol{\psi}}(\tilde{w} + \boldsymbol{\sigma})\right)(t),$$

where  $\tilde{w} \in C^1_{\xi;\psi}(J)$  be a function satisfying the functional equation

$$\tilde{w}(t) = f(t, x(t)).$$

Hence, for each  $t \in (a, b]$ , we have

$$\begin{aligned} |x(t) - y(t)| &\leq \left( \mathscr{J}_{a+}^{\vartheta,k;\Psi} |\tilde{w}(s) - w(s)| \right)(t) + \left( \mathscr{J}_{a+}^{\vartheta,k;\Psi} \sigma \right)(t) \\ &\leq \varepsilon \kappa_{\nu} v(t) + \frac{\eta}{k \Gamma_k(\vartheta)} \int_a^t \frac{\psi'(s) |x(s) - y(s)| dt}{(\psi(t) - \psi(s))^{1-\frac{\vartheta}{k}}}. \end{aligned}$$

By applying Lemma 9, we obtain

$$\begin{aligned} |x(t) - y(t)| &\leq \varepsilon \kappa_{\nu} v(t) + \int_{a}^{t} \sum_{i=1}^{\infty} \frac{(\eta)^{i}}{k \Gamma_{k}(\vartheta i)} \psi'(s) [\psi(t) - \psi(s)]^{\frac{i\vartheta}{k} - 1} \varepsilon \kappa_{\nu} v(s) ds, \\ &\leq \varepsilon \kappa_{\nu} v(t) \mathbb{E}_{k}^{\vartheta, k} \begin{bmatrix} \eta (\psi(t) - \psi(a))^{\frac{\vartheta}{k}} \\ \eta (\psi(b) - \psi(a))^{\frac{\vartheta}{k}} \end{bmatrix} \\ &\leq \varepsilon \kappa_{\nu} v(t) \mathbb{E}_{k}^{\vartheta, k} \begin{bmatrix} \eta (\psi(b) - \psi(a))^{\frac{\vartheta}{k}} \end{bmatrix}. \end{aligned}$$

Then for each  $t \in (a, b]$ , we have

$$|x(t) - y(t)| \le a_{f,v} \varepsilon v(t),$$

where

$$a_{f,v} = \kappa_{v} \mathbb{E}_{k}^{\vartheta,k} \left[ \eta \left( \psi(b) - \psi(a) \right)^{\frac{\vartheta}{k}} \right]$$

Hence, the problem (1)-(2) is U-H-R stable with respect to v.

#### 5. EXAMPLES

With the following examples, we look at particular cases of the problem (1)-(2).

**Example 1** Taking  $r \to 0$ ,  $\vartheta = \frac{1}{2}$ , k = 1,  $\psi(t) = t$ , a = 1, b = 2 and  $x_0 = 1$ , we obtain a particular case of problem (1)-(2) with Riemann-Liouville fractional derivative, given by

$$\begin{pmatrix} H \mathscr{D}_{1+}^{\frac{1}{2},0;\Psi} x \\ 1 \end{pmatrix} (t) = \begin{pmatrix} RL \mathbb{D}_{1+}^{\frac{1}{2}} x \end{pmatrix} (t) = f(t,x(t)), \ t \in (1,2],$$
(11)

$$\left(\mathscr{J}_{1+}^{\frac{1}{2},1;\psi}x\right)(1^{+}) = 1,$$
(12)

where J = [1, 2],  $\xi = \frac{1}{k}(r(k - \vartheta) + \vartheta) = \frac{1}{2}$  and

$$f(t,x) = \frac{\sqrt{t-1}|\sin(t)|(1+x)}{120e^{-t+3}}, \ t \in J, \ x \in \mathbb{R}.$$

We have

$$C_{\xi;\psi}(J) = C_{\frac{1}{2};\psi}(J) = \left\{ u: (1,2] \to \mathbb{R}: (\sqrt{t-1})u \in C(J,\mathbb{R}) \right\},$$

and

$$C^{1}_{\xi;\psi}(J) = C^{1}_{\frac{1}{2};\psi}(J) = \left\{ u \in C_{\frac{1}{2};\psi}(J) : u' \in C_{\frac{1}{2};\psi}(J) \right\},\$$

Since the continuous function  $f \in C^1_{\frac{1}{2}; \psi}(J)$ , then the condition (Cd.1) is satisfied. For each  $x, y \in \mathbb{R}$  and  $t \in J$ , we have

$$|f(t,x) - f(t,y)| \le \frac{\sqrt{t-1}|\sin(t)|}{120e^{-t+3}}|x-y|, \ t \in J,$$

and so the condition (Cd.2) is satisfied with  $\eta = \frac{1}{120e}$ . Also, the condition (9) of Theorem 12 is satisfied. Indeed, we have

$$\mathscr{L} = \frac{\sqrt{\pi}}{120e} \approx 0,00543374443477744 < 1.$$

Then the problem (11)–(12) has a unique solution in  $C^1_{\frac{1}{2};\psi}([1,2])$ .

*Now, if we take* v(t) = t - 1 *and*  $\kappa_v = \frac{\sqrt{2}\Gamma(2)}{\Gamma(\frac{5}{2})}$ *, then for each*  $t \in J$ *, we get* 

$$\begin{pmatrix} \mathscr{J}_{1+}^{\frac{1}{2},1;\psi} v \end{pmatrix}(t) &\leq \frac{\sqrt{2}\Gamma(2)}{\Gamma(\frac{5}{2})}(t-1) \\ &= \kappa_{v}v(t), \end{cases}$$

which shows that the hypothesis (Cd.3) is satisfied. Consequently, Theorem 13 implies that the problem (11)-(12) is U-H-R stable.

**Example 2** Taking  $r \to 0$ ,  $\vartheta = \frac{1}{2}$ , k = 1,  $\psi(t) = \ln t$ , a = 1, b = e and  $x_0 = \pi$ , we get a particular case of problem (1) - (2) using the Hadamard fractional derivative, given by

$$\begin{pmatrix} H & \mathcal{D}_{1+}^{\frac{1}{2},0;\Psi} x \\ 1 & \mathcal{D}_{1+}^{\frac{1}{2},0;\Psi} x \end{pmatrix} (t) = \begin{pmatrix} H & \mathcal{D}_{1+}^{\frac{1}{2}} x \\ 0 & 1 \end{pmatrix} (t) = f(t,x(t)), \ t \in (1,e],$$
(13)

$$\left(\mathscr{J}_{1+}^{\frac{1}{2},1;\psi}x\right)(1^{+}) = \pi,$$
(14)

where J = [1, e], and

$$f(t,x,y) = \frac{e+x}{222e^t}, \ t \in J, \ x \in \mathbb{R}.$$

We have

$$C_{\xi;\psi}(J) = C_{\frac{1}{2};\psi}(J) = \left\{ u: (1,e] \to \mathbb{R}: (\sqrt{\ln t})u \in C(J,\mathbb{R}) \right\},\$$

and

$$C^{1}_{\xi;\psi}(J) = C^{1}_{\frac{1}{2};\psi}(J) = \left\{ u \in C_{\frac{1}{2};\psi}(J) : u' \in C_{\frac{1}{2};\psi}(J) \right\},\$$

Clearly, the function  $f \in C^1_{\frac{1}{2};\psi}(J)$ . Hence condition (Cd.1) is satisfied. For each  $x, y, \in \mathbb{R}$  and  $t \in J$ , we have

$$|f(t,x) - f(t,y)| \le \frac{1}{222e^t} |x - y|, t \in J,$$

and so the condition (Cd.2) is satisfied with  $\eta = \frac{1}{222e}$  Also, we have

$$\mathscr{L} = rac{\sqrt{\pi}}{222e} pprox 0.00293715915393375 < 1,$$

then, the condition (9) of Theorem 12 is satisfied. Then the problem (13)–(14) has a unique solution in  $C_{\frac{1}{2};\psi}([1,e])$ . The problem is also U-H-R stable if we take  $v(t) = e^2$  and  $\kappa_v = \frac{1}{\Gamma(\frac{3}{2})}$ . Indeed, for each  $t \in J$ , we get

$$\begin{pmatrix} \mathscr{J}_{1+}^{\frac{1}{2},1;\psi}v \end{pmatrix}(t) &\leq \frac{e^2}{\Gamma(\frac{3}{2})} \\ &= \kappa_{\nu}v(t). \end{cases}$$

#### 6. REFERENCES

- [1] S. Abbas, M. Benchohra, J. R. Graef and J. Henderson, *Implicit Differential and Integral Equations : Existence and stability*, Walter de Gruyter, London, 2018.
- [2] S. Abbas, M. Benchohra and G. M. N'Guérékata, Advanced Fractional Differential and Integral Equations, Nova Science Publishers, New York, 2014.
- [3] S. Abbas, M. Benchohra and G. M. N'Guérékata, *Topics in Fractional Differential Equations*, Springer-Verlag, New York, 2012.
- [4] B. Ahmad, A. Alsaedi, S.K. Ntouyas, J. Tariboon, *Hadamard-type Fractional Differential Equations, Inclusions and Inequalities.* Springer, Cham, 2017.
- [5] Y. M. Chu, M. U. Awan, S. Talib, M. A. Noor and K. I. Noor, Generalizations of Hermite–Hadamard like inequalities involving  $\chi_{\kappa}$ -Hilfer fractional integrals, *Adv. Difference Equ.* **2020** (2020), 594.
- [6] R. Diaz and C. Teruel, q,k-Generalized gamma and beta functions, J. Nonlinear Math. Phys 12 (2005), 118-134.
- [7] A. Granas and J. Dugundji, Fixed Point Theory, Springer-Verlag, New York, 2003.
- [8] A.A. Kilbas, H. M. Srivastava, and Juan J. Trujillo, *Theory and Applications of Fractional Differential Equations*. North-Holland Mathematics Studies, Amsterdam, 2006.

- [9] J. E. Lazreg, S. Abbas, M. Benchohra, and E. Karapinar, Impulsive Caputo-Fabrizio fractional differential equations in b-metric spaces, *Open Mathematics*. **19** (2021), 363-372.
- [10] S. Mubeen and G. M. Habibullah, k-Fractional Integrals and Application, Int. J. Contemp. Math. Sciences, 7 (2012), 89-94.
- [11] J. E. Nápoles Valdés, Generalized fractional Hilfer integral and derivative, *Contr. Math.* 2 (2020), 55-60.
- [12] S. Naz and M. N. Naeem, On the Generalization of k-Fractional Hilfer-Katugampola Derivative with Cauchy Problem, *Turk. J. Math.* 45 (2021), 110-124.
- [13] S. Rashid, M. Aslam Noor, K. Inayat Noor, Y. M. Chu, Ostrowski type inequalities in the sense of generalized *H*-fractional integral operator for exponentially convex functions, *AIMS Mathematics* 5 (2020), 2629-2645.
- [14] A. Salim, J. E. Lazreg, B. Ahmad, M. Benchohra, and J. J. Nieto, A Study on k-Generalized ψ-Hilfer Derivative Operator. (submitted).
- [15] A. Salim, M. Benchohra, J. R. Graef and J. E. Lazreg, Boundary value problem for fractional generalized Hilfer-type fractional derivative with non-instantaneous impulses, *Fractal Fract.* 5 (2021), 1-21.
- [16] A. Salim, M. Benchohra, E. Karapinar and J. E. Lazreg, Existence and Ulam stability for impulsive generalized Hilfer-type fractional differential equations, *Adv. Difference Equ.* 2020 (2020), 601.
- [17] A. Salim, M. Benchohra, J. E. Lazreg and J. Henderson, Nonlinear implicit generalized Hilfer-type fractional differential equations with non-instantaneous impulses in Banach spaces, *Adv. Theory Nonlinear Anal. Appl.* 4 (2020), 332-348.
- [18] A. Salim, M. Benchohra, J. E. Lazreg and G. N'Guérékata, Boundary value problem for nonlinear implicit generalized Hilfer-type fractional differential equations with impulses. *Abstr. Appl. Anal.* 2021 (2021), 17pp.
- [19] A. Salim, M. Benchohra, J. E. Lazreg, J. J. Nieto and Y. Zhou, Nonlocal initial value problem for hybrid generalized Hilfer-type fractional implicit differential equations. *Nonauton. Dyn. Syst.* 8 (2021), 87-100.
- [20] J. V. da C. Sousa, G. S. F. Frederico, and E. C. de Oliveira, ψ-Hilfer pseudo-fractional operator : new results about fractional calculus, *Comp. Appl. Math.* **39** (2020), p. 254.
- [21] J. V. da C. Sousa and E. C. de Oliveira, On the  $\psi$ -Hilfer fractional derivative, *Commun. Nonlinear Sci. Numer. Simul.* **60** (2018), 72-91.
- [22] J. V. da C. Sousa, M. A. P. Pulido, and E. C. de Oliveira, Existence and Regularity of Weak Solutions for  $\psi$ -Hilfer Fractional Boundary Value Problem, *Mediterr. J. Math.* **18** (2021), p. 147.
- [23] Y. Zhou, J.R Wang and L. Zhang Basic Theory of Fractional Differential Equations, World Scientific, Singapore, 2017.