

# COMMON FIXED POINT FOR MULTIVALUED ( $\psi, \theta, G$ )-CONTRACTION TYPE MAPS IN METRIC SPACES WITH A GRAPH STRUCTURE

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## ABSTRACT

In this work, we introduce the notion of a common  $(\psi, \theta, G)$ -contraction multi-valued mapping in order to establish some new common fixed point theorems for these classes of mappings in complete metric spaces endowed with a graph. An example of application illustrates the main existence result. Our results generalize some recent known results.

## 1. INTRODUCTION

Since the proof of Banach's fixed contraction principle [2], many research works have considered different kinds of generalizations. Among them, the classical multi-valued version was established by Covitz and Nadler [11] in 1969 using the Hausdorff-Pompeiu metric in a complete metric space.

In 2008, Jachymski [7] introduced a new approach in metric fixed point theory by replacing the order structure with a graph structure on a metric space. They introduced the concept of  $G$ -contraction, that is a single-valued contraction mapping in a metric space with a graph. Afterwards, many authors extended the Banach  $G$ -contraction in different ways (we refer to [1], [3], [12], [14], [15] and references therein).

Recently, Jleli and Samet [9] introduced the  $\theta$ -contraction and proved a fixed point result as a generalization of the Banach contraction principle. In turn, their result has also been extended by many authors (see, e.g., [5], [6], [8], [10], [16]).

Consistent with [9], we denote by  $\Theta$  the set of all functions  $\theta : (0, \infty) \rightarrow (1, \infty)$  satisfying the following conditions :

( $\Theta_1$ )  $\theta$  is non-decreasing,

( $\Theta_2$ ) for each sequence  $(t_n)_n \subset (0, \infty)$ ,  $\lim_{n \rightarrow \infty} \theta(t_n) = 1$  if and only if  $\lim_{n \rightarrow \infty} t_n = 0^+$ ,

( $\Theta_3$ ) there exist  $r \in (0, 1)$  and  $l \in (0, \infty]$  such that  $\lim_{t \rightarrow 0^+} \frac{\theta(t)-1}{t^r} = l$ .

The aim of this paper is to prove some common fixed point results for  $(\psi, \theta, G)$ -contractions multi-valued mappings in a metric space endowed with a graph  $G$ .

First of all, we collect some basic notions and primary results we need to develop our results.

Let  $(X, d)$  be a metric space. We shall denote by  $CB(X)$  the family of nonempty closed bounded subsets of  $X$  and by  $C(X)$  the family of nonempty closed subsets of  $X$ . For  $A, B \in C(X)$ ,

let

$$H(A, B) = \max\left\{\sup_{x \in A} d(x, B), \sup_{y \in B} d(y, A)\right\},$$

where  $d(x, B) = \inf\{d(x, y) : y \in B\}$ .  $H$  is called the Hausdorff-Pompeiu distance on  $C(X)$ . This is a metric on  $CB(X)$ .

A graph  $G$  is an ordered pair  $(V, E)$ , where  $V$  is a set and  $E \subset V \times V$  is a binary relation on  $V$ . Elements of  $E$  are called edges and are denoted by  $E(G)$  while elements of  $V$ , denoted  $V(G)$ , are called vertices. If the direction is imposed in  $E$ , that is the edges are directed, then we get a digraph (directed graph). Hereafter, we assume that  $G$  has no parallel edges, i.e. two vertices cannot be connected by more than one edge. Thus,  $G$  can be identified with the pair  $(V(G), E(G))$ . If  $x$  and  $y$  are vertices of  $G$ , then a path in  $G$  from  $x$  to  $y$  of length  $k \in \mathbb{N}$  is a finite sequence  $(x_n)_n$ ,  $n \in \{0, 1, 2, \dots, k\}$  of vertices such that  $x = x_0, \dots, x_k = y$  and  $(x_{n-1}, x_n) \in E(G)$  for  $n \in \{1, 2, \dots, k\}$ . A graph  $G$  is connected if there is a path between any two vertices and it is weakly connected if  $\tilde{G}$  is connected, where  $\tilde{G}$  denotes the undirected graph obtained from  $G$  by ignoring the direction of edges. Let  $G^{-1}$  be the graph obtained from  $G$  by reversing the direction of edges (the conversion of the graph  $G$ ). We have

$$E(G^{-1}) = \{(x, y) \in X \times X : (y, x) \in E(G)\}.$$

It is more convenient to treat  $\tilde{G}$  as a directed graph for which the set of edges is symmetric. Then

$$E(\tilde{G}) = E(G) \cup E(G^{-1}).$$

Let  $G_x$  be the component of  $G$  consisting of all the edges and vertices which are contained in some path in  $G$  beginning at  $x$ . If  $G$  is such that  $E(G)$  is symmetric, then for  $x \in V(G)$ , we may define the equivalence class  $[x]_G$  on  $V(G)$  by the relation  $xRy$  if there is a path in  $G$  from  $x$  to  $y$ . Then  $V(G_x) = [x]_G$ .

Throughout this paper,  $(X, d)$  denotes a metric space,  $G = (V(G), E(G))$  is a directed graph without parallel edges with  $V(G) = X$  and  $(x, x) \notin E(G)$  (the graph does not contain loops). The following condition first appeared in [7] :

**Property (A) :** for any sequence  $(x_n)_n$  in  $X$ , if  $x_n \rightarrow x$  and  $(x_n, x_{n+1}) \in E(G)$ , for all  $n \in \mathbb{N}$ , then  $(x_n, x) \in E(G)$  for  $n \in \mathbb{N}$ .

With this condition, Jachymski showed that in a complete metric space, a  $G$ -contraction has a fixed if and only if  $X_f \neq \emptyset$ , where

$$X_f = \{x \in X : (x, f(x)) \in E(G)\}. \quad (1)$$

## 2. MAIN RESULT

Consider the following classes of functions :

**Definition 1** We denote by  $\Psi$  the set of functions  $\psi : (1, \infty) \rightarrow (1, \infty)$  satisfying the following conditions :

(i)  $\psi$  is non-decreasing ;

(ii) for each sequence  $(t_n)_n \subset (1, \infty)$ ,  $\lim_{n \rightarrow \infty} \psi(t_n) = 1$  if and only if  $\lim_{n \rightarrow \infty} t_n = 1$ .

Now we give the following definition

**Definition 2** Let  $(X, d)$  be a metric space endowed with a graph  $G$ . Two mappings  $T_1, T_2 : X \rightarrow C(X)$  are said to be a common  $(\psi, \theta, G)$ -contraction if for all  $x, y \in X$  such that  $(x, y) \in E(G)$  and  $a \in T_i(x)$ , there exists  $b \in T_j(y)$  for  $i, j \in \{1, 2\}$  with  $i \neq j$  such that  $(a, b) \in E(G)$  and

$$\psi(\theta(d^p(a, b))) \leq \psi([\theta((M_p(T_i x, T_j y))]^{k(d(x, y))}) + LN_p(T_i x, T_j y),$$

where

$$N_p(T_i x, T_j y) = \min\{d^p(x, T_i(x)), d^p(y, T_j(y)), d^p(y, T_i(x)), d^p(x, T_j(y))\},$$

$$M_p(T_i x, T_j y) = \max\left\{d^p(x, y), d^p(x, T_i(x)), d^p(y, T_j(y)), \frac{d^p(y, T_i(x)) + d^p(x, T_j(y))}{1 + d^p(x, y)}, \frac{d^p(x, T_i(x))d^p(y, T_j(y))}{1 + d^p(x, y)}, \frac{d^p(y, T_i(x))d^p(x, T_j(y))}{1 + d^p(x, y)}\right\},$$

$k : (0, +\infty) \rightarrow [0, 1)$  satisfies  $\limsup_{s \rightarrow t^+} k(s) < 1$ , for all  $t \in [0, +\infty)$ ,  $L \geq 0$ ,  $\theta \in \Theta$ ,  $\psi \in \Psi$ ,  $\psi \circ \theta$  is lower semi continuity, and  $1 \leq p < \frac{1}{r}$ .

Our existence results for common fixed points are collected in the following :

**Theorem 1** Let  $(X, d)$  be a complete metric space endowed with a directed graph  $G$  and suppose that the triple  $(X, d, G)$  has the property (A). Let  $T_1, T_2 : X \rightarrow C(X)$  be a common  $(\psi, \theta, G)$ -contraction. Then the following statements hold :

- (1) For every  $x \in X_{T_i}$ ,  $i = 1$  or  $i = 2$ , the mappings  $T_1, T_2|_{[x]_{\bar{G}}}$  have a common fixed point, where  $X_{T_i}$  is as defined in (1).
- (2) If  $X_{T_i} \neq \emptyset$ ,  $i = 1$  or  $i = 2$ , and  $G$  is weakly connected, then  $T_1$  and  $T_2$  have a common fixed point in  $X$ .
- (3) If  $X' = \cup\{[x]_{\bar{G}} : x \in X_{T_i}\}$ ,  $i = 1$  or  $i = 2$ , then  $T_1, T_2|_{X'}$  have a common fixed point.
- (4) If  $\text{Graph}(T_i) \subseteq E(G)$ ,  $i = 1$  or  $i = 2$ , then  $T_1$  and  $T_2$  have a common fixed point.

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